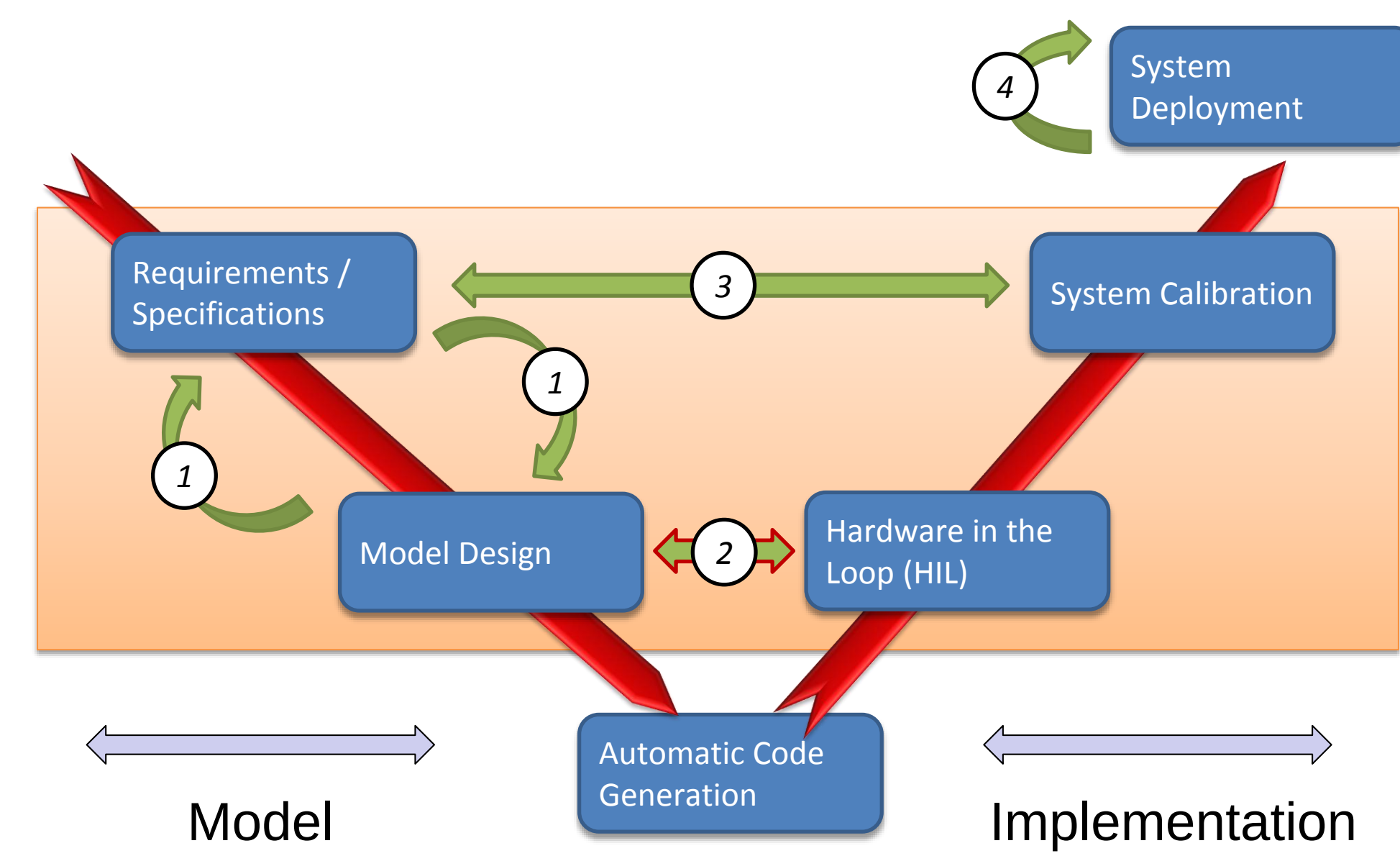


Model-Based Design V Process

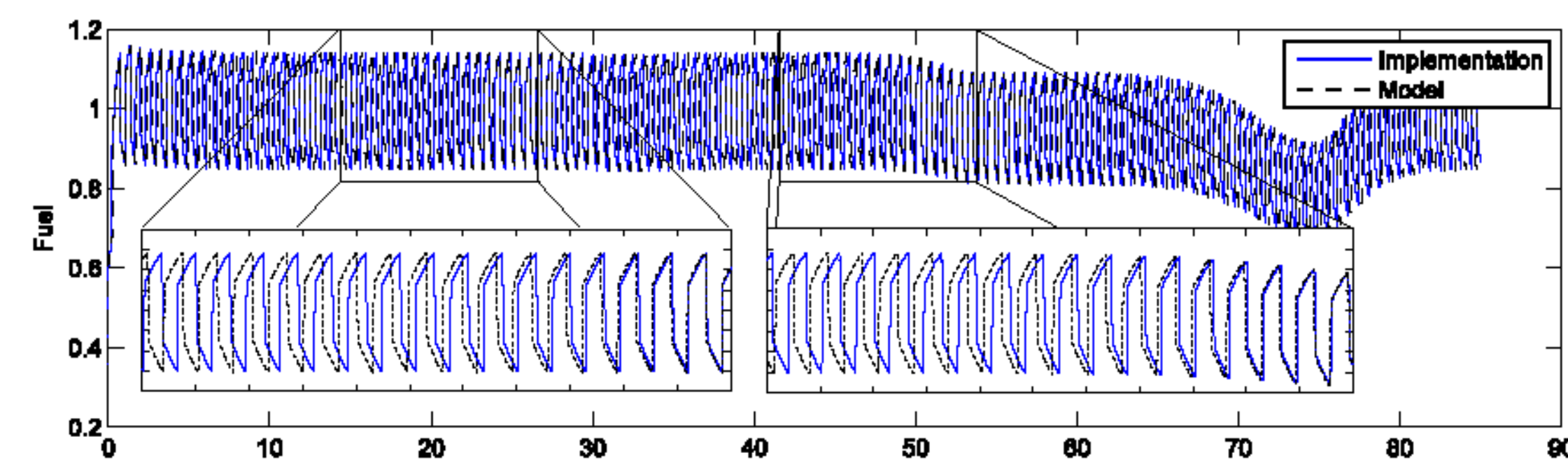


Problem:

- How to formalize the notion that the outputs of the Implementation (right-hand side) “look like” those of the Model (left-hand side), both in signal values and timing characteristics?
- How to compute such a closeness measure?
- What can we infer about satisfied properties?

A generic conformance notion

In general, determining that the outputs of the Model and the Implementation are “close enough”, i.e. **conformant**, is application-dependent and relies on expertise and ad-hoc rules.



We propose $(T, J, \tau, \varepsilon)$ -closeness as a generic conformance notion. This notion is appropriate for continuous-time, discrete-time, and hybrid-time systems.

Benefits of $(T, J, \tau, \varepsilon)$ -closeness as a generic notion of conformance:

- Only requires the ability to simulate the system – black boxes O.K.
- Can be tested early in the design cycle before all the instrumentation is in place for more targeted testing.
- Captures differences in timing characteristics as well as signal values
- Real-valued: can speak of a **conformance degree** and rank Implementations based on how well they conform to the Model.

Related work: distance between systems

- Input-Output Conformance (Tretmans) for discrete Labeled Transition Systems and Hybrid IOCO (Van Osch) for Hybrid Transition Systems.
- Woehrle et al. verify *conformance to a specification* (and not between systems)
- Modeling by Discrete Action Systems (Brandl et al.)
- Directional Hausdorff distance (Abate et al.)
- (τ, ε) -similar traces (Quesel)
- Skorokhod metrics with bijective re-timings (Caspi et al.) or set-valued re-timings (Davoren)
- Approximate synchronization and bisimulation (Julius et al.)

J.-D. Quesel. *Similarity, Logic, and Games: Bridging Modeling Layers of Hybrid Systems*. PhD thesis, Carl Von Ossietzky Universität Oldenburg, 2013.
A.A. Julius and G.J. Pappas. Approximate equivalence and approximate synchronization of metric transition systems, *CDC 2006*

Conformance Testing as Falsification for Cyber-Physical Systems

Houssam Abbas⁽¹⁾, Bardh Hoxha⁽¹⁾, Georgios Fainekos⁽¹⁾, Jyotirmoy Deshmukh⁽²⁾, James Kapinski⁽²⁾ and Koichi Ueda⁽²⁾

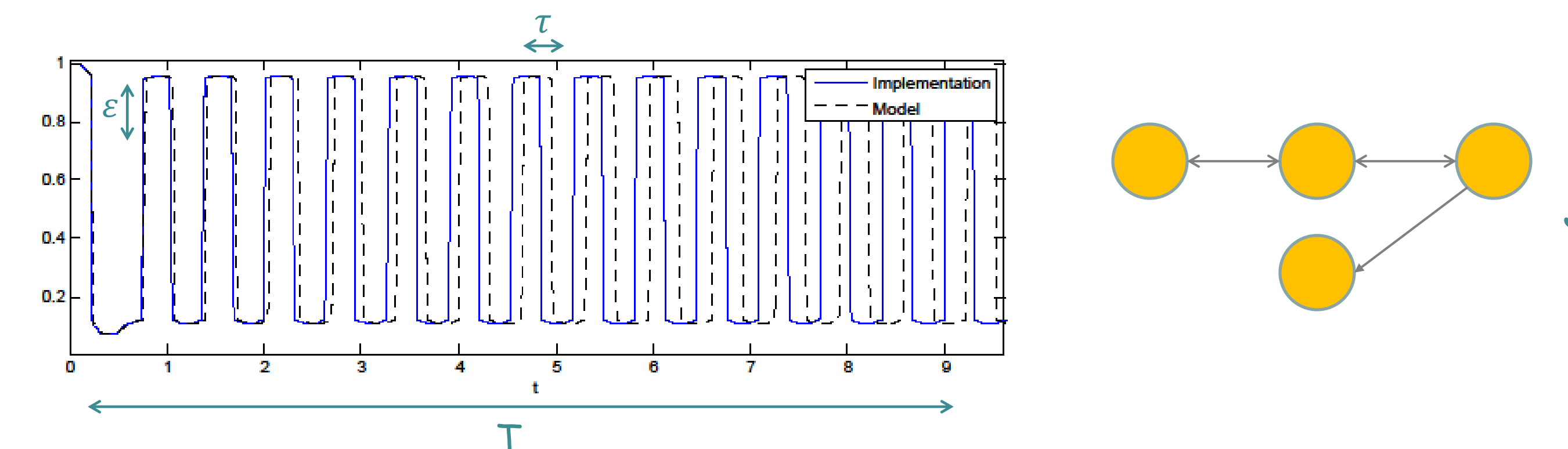


Sponsors: CNS 1116136, CNS 1319560, IIP-0856090, NSF, CENTER FOR EMBEDDED SYSTEMS an NSF Industry/University Cooperative Research Center

$(T, J, \tau, \varepsilon)$ -closeness

Consider two trajectories y and y' of Σ and Σ' , respectively. Given $T > 0$, $J > 0$, $\tau > 0$, and $\varepsilon > 0$, we say y and y' are $(T, J, \tau, \varepsilon)$ -close if:

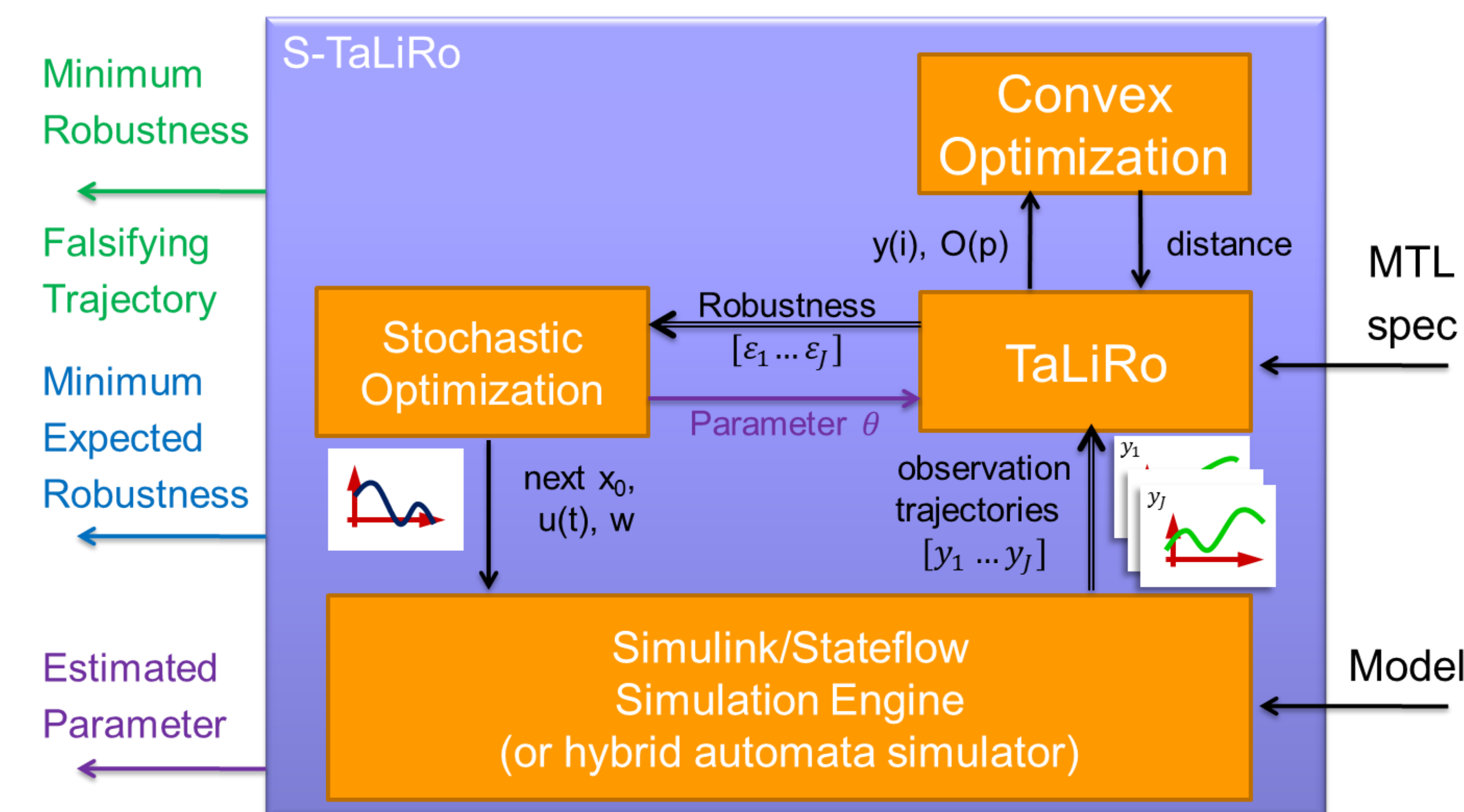
- For all (t, j) in the support of y s.t. $t \leq T$ and $j \leq J$, there exists (s, i) in the support of y' , such that $|t - s| < \tau$ and $\|y(t, j) - y'(s, i)\| < \varepsilon$
- For all (t, j) in the support of y' , s.t. $t \leq T$ and $j \leq J$, there exists (s, i) in the support of y , such that $|t - s| < \tau$ and $\|y'(t, j) - y(s, i)\| < \varepsilon$



The largest (τ, ε) such that all trajectories of Σ and Σ' are $(T, J, \tau, \varepsilon)$ -close is the **conformance degree** between Σ and Σ' .

R. Goebel and A.R. Teel. Solutions to hybrid inclusions via set and graphical convergence with stability theory applications. *Automatica*, 2006.
R. G. Sanfelice and A. R. Teel. Dynamical properties of hybrid systems simulators. *Automatica*, 2010.

Implemented in the S-TaLiRo Toolbox



www.tinyurl.com/Staliro

High-fidelity engine model

56 state variables and black boxes

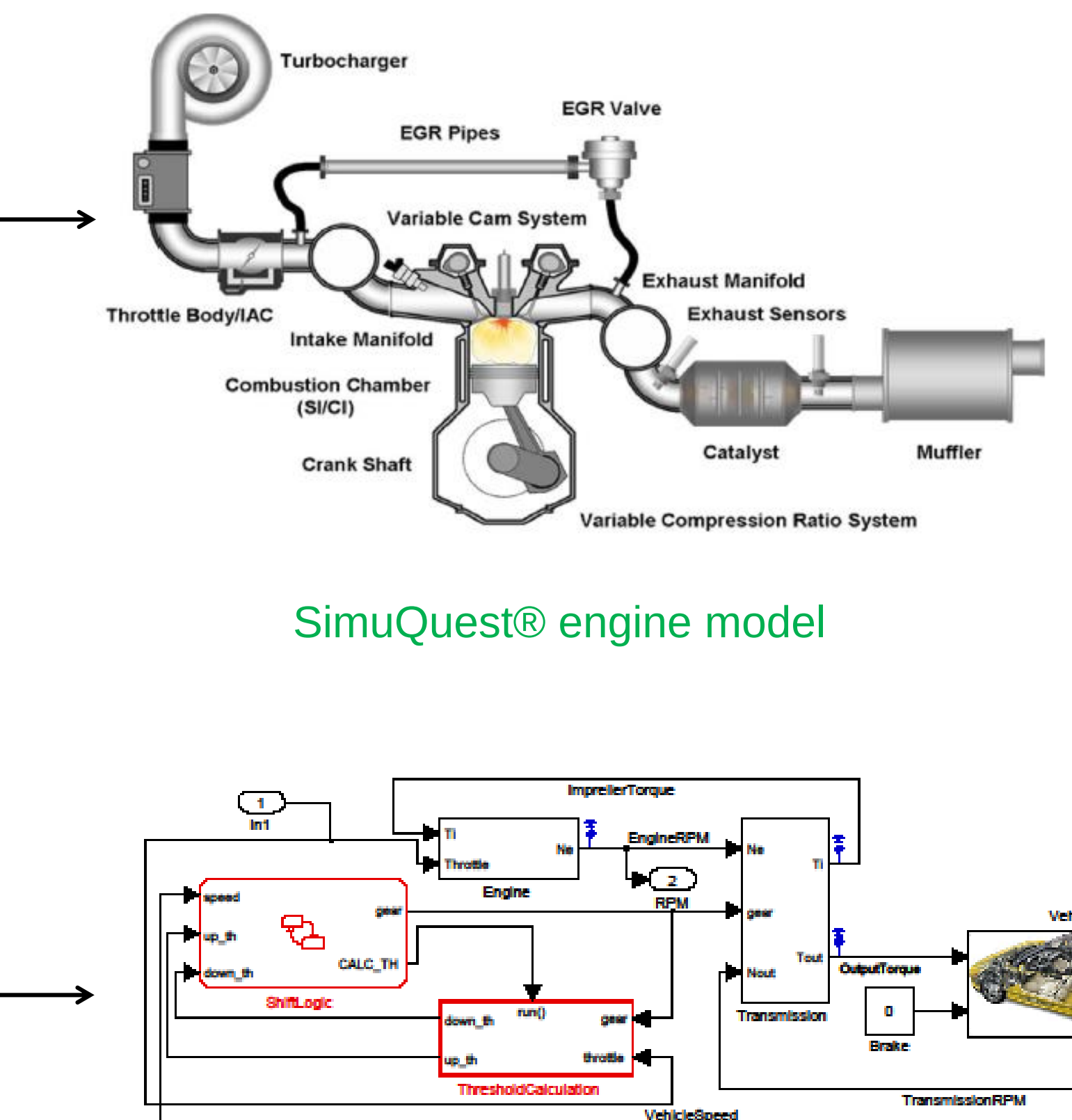
Modeling from physics first principles

LUTs, FSMs and regression models

Input signal

Nonlinear dynamics

LUTs and FSMs



MathWorks® Automatic Transmission model

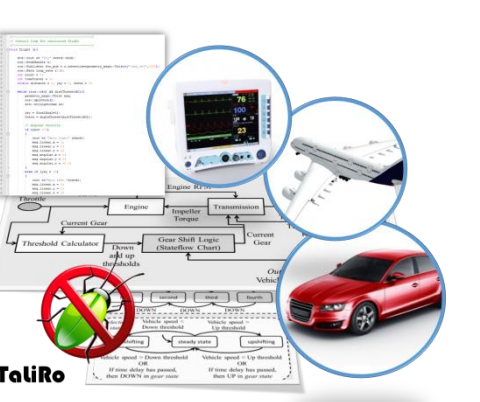
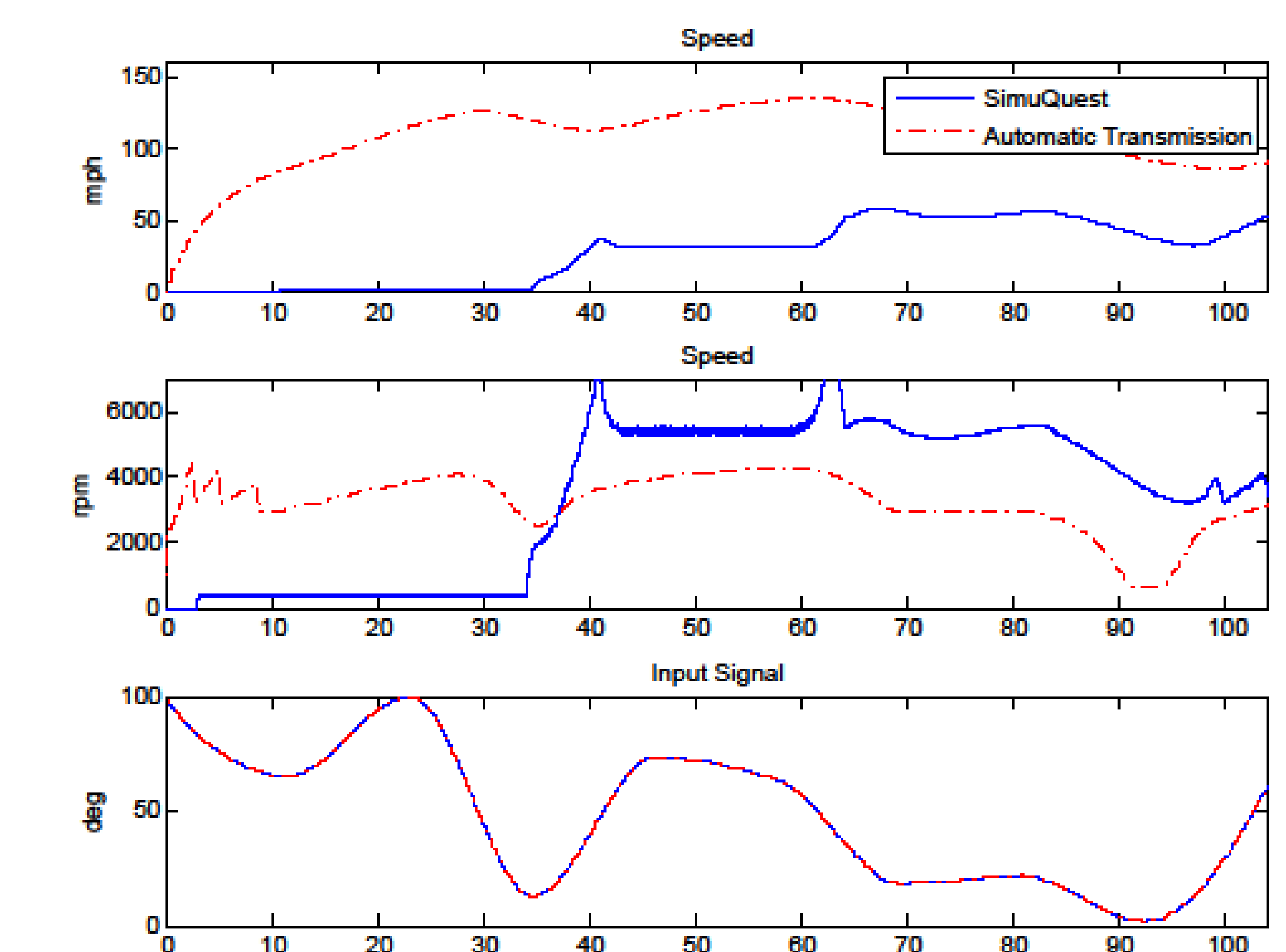
Conformance testing results

The (τ, ε) pairs are partially ordered, so must fix one parameter and optimize the other.

We fix τ and maximize ε , for pre-defined values of the horizon (T, J) .

We use Simulated Annealing to maximize ε : it is a stochastic, global, derivative-free optimizer. It converges in probability to the global maximum with known bounds on the convergence rate.

H. Haario and E. Saksman. Simulated annealing in general state space. *Advances in Applied Probability*, 23:866–893, 1991.



Sample result: the two systems are $(104, J_{MAX}, 5 \cdot 10^{-4}, 1)$ -close with high probability. This constitutes a *lower bound* on the true conformance degree.